

Super- Tactical (TAC) Inertial Measurement Unit (IMU)

The EMCORE Super-TAC IMU bridges the performance gap between tactical grade and navigation grade inertial measurement units in a small, lightweight robust package.



DESCRIPTION

The Super-TAC IMU integrates three fiber optic gyros that exceed tactical grade performance with three high-accuracy Micro-Electro-Mechanical Systems (MEMS) accelerometers and state-of-the-art support electronics in a single small, lightweight package. This solution addresses the need for superior inertial performance in a tactical-grade package, critical for operation in GPS denied and contested environments.

The Super-TAC IMU measures change in velocity and angle, utilizing a configurable variable synchronous data link control (SDLC) digital serial bus. The Super-TAC is configured to offer customers the best value solution when designing new systems as well as provide the flexibility to upgrade existing platforms.

The Super-TAC IMU employs state-of-the-art optics with fewer components, providing significant performance and reliability improvements across standard military environments.

BACKGROUND

EMCORE Space & Navigation, located in Budd Lake, NJ has been designing, developing and producing inertial components, sensors and navigation systems for Space, Ground, and Avionic applications for over 75 years. EMCORE has been developing Fiber Optic Gyros (FOGs) since the early 1990s, producing and delivering IMU products with performance ranging from tactical to strategic grade.



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APPLICATIONS:

The EMCORE Super-TAC IMU offers the highest bias stability and angle random walk available in tactical-grade inertial measurement units and is designed to be used in Avionic, Missile, Ground, Marine applications. The following is a representative list of system applications:

- Electro-optical/FUR/Camera/Radar/
Laser Pointing/ Stabilization
- Guidance/Navigation
- Motion Compensation
- Target Location Systems
- AHRS
- Autonomous Vehicle
- GNSS-aiding
- Oil and gas exploration
- Mapping/Survey
- UAV/UUV Flight Controls

PERFORMANCE

GYRO PERFORMANCE

Bias Stability	$< 0.05 \text{ } ^\circ/\text{hr. (1}\sigma\text{)}$
Angle Random Walk (ARW)	$\leq 0.01 \text{ } ^\circ/\sqrt{\text{hr. (1}\sigma\text{)}}$
Scale Factor Repeatability	$\leq 100 \text{ ppm (1}\sigma\text{)}$
Scale Factor Linearity	$\leq 50 \text{ ppm (1}\sigma\text{)}$
Angular Rate Range	$1,000 \text{ } ^\circ/\text{sec}$
Acceleration Range	$100,000 \text{ } ^\circ/\text{sec}^2$

ACCELEROMETER PERFORMANCE

Range	$\pm 25 \text{ g}$
Bias Variation	$\leq 50 \text{ } \mu\text{g (1}\sigma\text{)}$
Scale Factor Stability	$\leq 300 \text{ ppm (1}\sigma\text{)}$

SYSTEM PERFORMANCE

Bandwidth (adjustable)	800 Hz (gyros) 150 Hz (accelerometers)
MTBF	$> 25,000 \text{ hr.}$



CHARACTERISTICS

Interface	RS-422 Synchronous Data Link Control (SDLC) Gigabit Ethernet optional
Power	10 W
Input Voltage	+5 VDC, $\pm 15 \text{ VDC}$

PHYSICAL

Weight	$< 1.65 \text{ lb. (< 750 gm)}$
Dimensions (not including connector)	3.52 in. diam. x 3.35 in. H 89.4 mm diam. x 85.1 mm H

ENVIRONMENTAL

Temperature Range	$-55 \text{ } ^\circ\text{C to } 71 \text{ } ^\circ\text{C}$ (continuous operation)
Random Vibration	15 grms
Shock	90 g, 6 ms terminal sawtooth
Humidity	$+60 \text{ } ^\circ\text{C}$ 95% relative humidity

NOTE: Product under qualification testing, performance and characteristics specifications are subject to change.

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